

Course code C.10. Course item

1. INFORMATION ABOUT THE COURSE

A. Basic information

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|---|--|
| Course title | Control Systems Analysis |
| Field of study | Computer Aided Engineering |
| Cycle | <i>Second</i> |
| Study profile | <i>Academic</i> |
| Study mode | <i>Full-time</i> |
| Specialisation | <i>Not relevant</i> |
| Unit responsible for the field of study | <i>Faculty of Mechanical Engineering</i> |
| Lecturer | <i>Dr hab. inż. Kazimierz Peszyński, prof. nadzw. UTP Dr inż. Sylwester Wawrzniak</i> |
| Introductory courses | <i>Fundamentals of Electronics and Electrical Engineering.</i> |
| Prerequisites | <i>Basic knowledge on the use of MATLAB (SCILAB) at the start of the course is an advantage, but not a necessity</i> |

B. Semester/ weekly timetable

| Semester | Lectures | Classes | Laboratories | Project classes | Seminars | Field experience | ECTS credits |
|----------|----------|---------|--------------|-----------------|----------|------------------|--------------|
| III | 15 | - | 15 | - | - | - | 2 |

LEARNING OUTCOMES (acc. to National Qualifications Framework)

| No. | Description of learning outcomes | Reference to learning outcomes for the field of study | Reference to learning outcomes for the area of study |
|------------------|---|---|--|
| KNOWLEDGE | | | |
| K1 | The student should be familiar with simulation software for objects and systems | CAE_W04 | T2A_W04, T2A_W05 |
| K2 | The graduate knows computational methods useful in modeling facilities and technical equipment | CAE_W02 | T2A_W03, T2A_W07 |
| SKILLS | | | |
| S1 | The student can simulate the behavior of the technical facilities and equipment using computer-aided tools, and on this basis can propose improvements to existing structures and systems | CAE_U02 | T2A_U09, T2A_U16, T2A_U17 |
| S2 | The student should be able to plan and carry out experiments and numerical simulations, interpret the results and draw conclusions | CAE_U12 | T2A_U08 |

| SOCIAL COMPETENCES | | | |
|--------------------|--|---------|---------|
| SC1 | The graduate can adequately define the priorities for implementation specified by his own or other tasks | CAE_K04 | T2A_K04 |

2. TEACHING METHODS

multimedia lecture, laboratory, demonstration, discussion

2. METHODS OF EXAMINATION

*Written examination, project and reports.
The reports will be derived through the course. The written exam will be multiple-choice exam.
The reports and the exam will be evaluated together.*

3. COURSE CONTENT

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| Specify the content separately for each type of classes in accordance with point I.B. | <p>LECTURES: Mathematical modeling of mechanical, electrical, fluid, and thermal systems. Transient and steady-state response analyses. Root locus and frequency analysis. Control systems analysis and design by the root-locus and method. Control systems analysis and design by the frequency-response method. PID controllers and modified PID controllers. Application of standard controllers and compensators. Control systems analysis in state space. The theory and methods reviewed are supported by many practical examples.</p> <p>LABORATORY: Matlab (SCILAB) simulations (step, frequency response of closed loop circuit, stability, modeling of basic mechanical, electrical, fluid, thermal processes and plants)</p> |
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4. VALIDATION OF LEARNING OUTCOMES

(Each learning outcome from the list requires validation methods to ensure that it was achieved by a student.)

| Learning outcome | Form of assessment (for example:) | | | | | |
|------------------|-----------------------------------|---------------------|------------|---------|--------|-------|
| | Oral examination | Written examination | Colloquium | Project | Report | |
| K1 | | x | | | | |
| S1 | | | | x | | |
| SC1 | | | | | x | |

5. LITERATURE

| | |
|--------------------------|--|
| Basic literature | <ol style="list-style-type: none"> 1) Ogata K., Modern Control Engineering, Third Edition, Prentice-Hall International, Inc., University of Minnesota 2004 2) Kuo B. C., Golnaraghi F, Automatic Control Systems –, John Wiley & Sons, 2003 3) Spong M.W, Hutchinson S., Vidyasagar M.. Robot Modeling and Control, John Wiley & Sons, Inc 2006 |
| Supplementary literature | <ol style="list-style-type: none"> 1) Houpis, C.H. and Lamont, G.B., Digital Control Systems, McGraw-Hill Book Co. New York, USA 1995 2) Azzo, J.J.D. and C.H. Houpis, Feedback control system analysis and synthesis, McGraw – Hill International, 3rd Edition, 1998. |

6. TOTAL STUDENT WORKLOAD REQUIRED TO ACHIEVE EXPECTED LEARNING OUTCOMES EXPRESSED IN TIME AND ECTS CREDITS

| Student's activity | Student workload– number of hours (for example:) |
|--|--|
| Participation in classes indicated in point 2.2 | 30 |
| Preparation for classes | 10 |
| Reading assignments | 10 |
| Other (preparation for exams, tests, carrying out a project etc) | 10 |
| Total student workload | 60 |
| Number of ECTS credits allocated by the lecturer | 2 |
| Final number of ECTS credits (determined by the Programme Council for the Field of Study) | 2 |